

skim

→ **UNDERSTANDING OCEAN
SURFACE MOTION**

Upgrading SWIM? The SKIM design

Presented by F. Ardhuin on behalf of SKIM Team
CFOSAT Science Team Meeting, March 2021

The ESA Earth Explorer 9 context



The “Sea surface KInematis Multiscale monitoring” mission candidate was a finalist for the EE9 competition...

but FORUM, the other candidate was selected in Sept. 2019

For implementation as EE9.

However, the successful phase A led to a recommendation to “find other ways and means” to implement SKIM.

Possible operational follow-up of SWIM on S3NG.

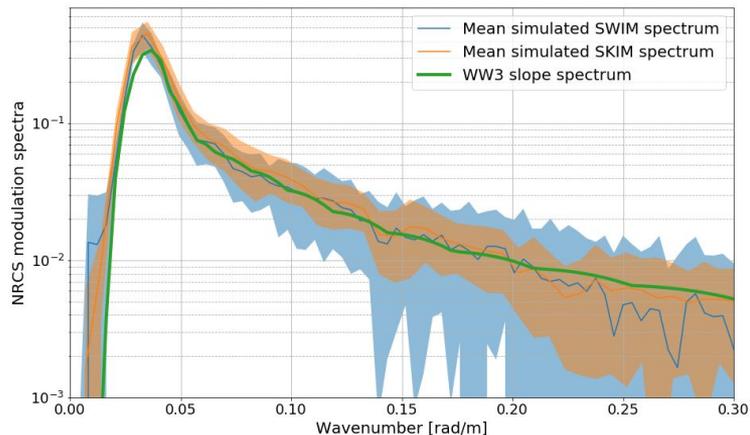
NB: SKIM’s goal for EE9 was focused on surface current, sea state was another important objective. Please see the “Report for Mission Selection” for full details.



SKIM vs SWIM

SKIM design is different from SWIM in many ways:

most important: **PRF (less noise)**, **footprint size (less directive)**, **Doppler**



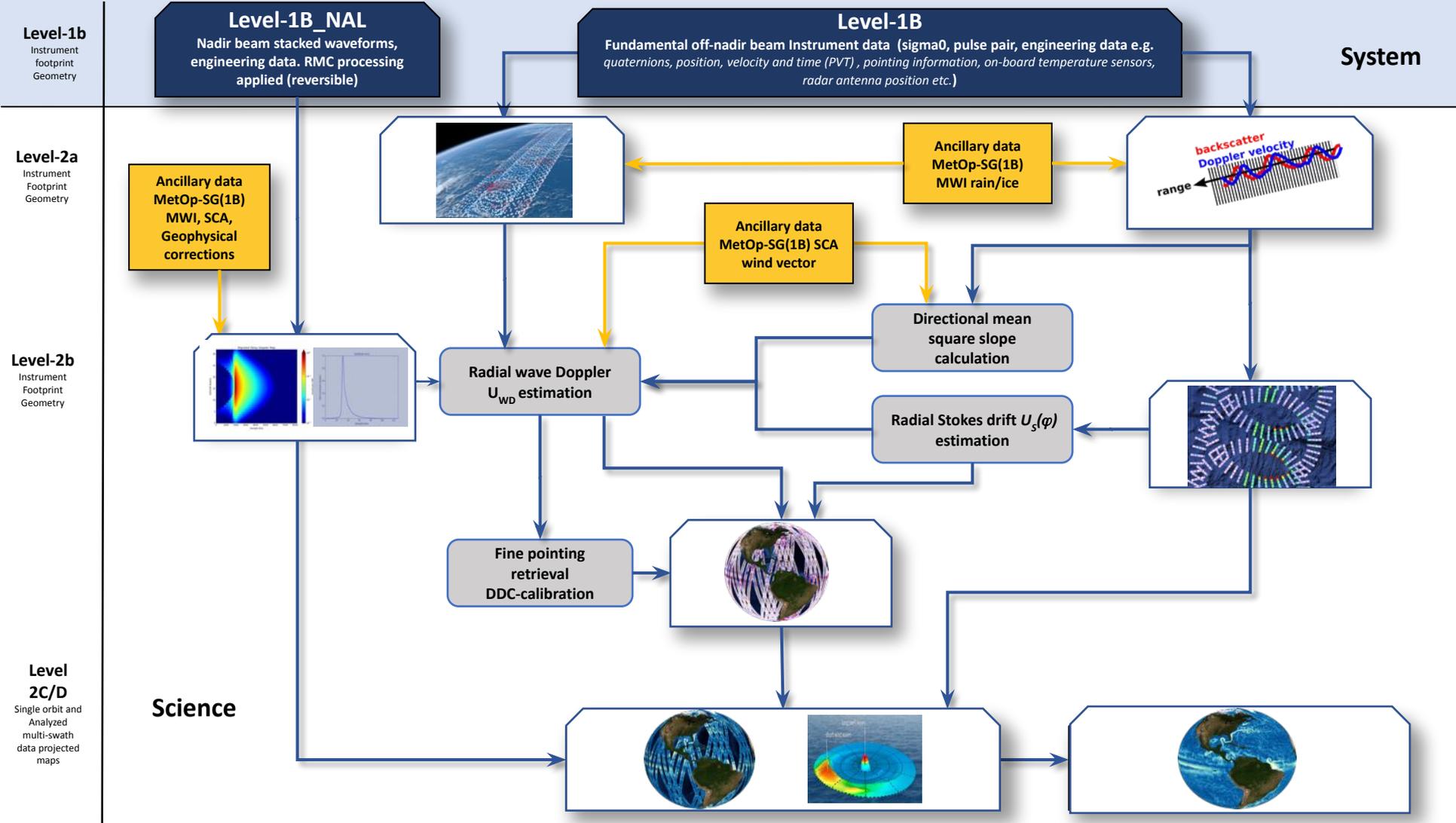
- WW3 spectrum (input to R3S simulator)
- Simulated SWIM spectra (100 realisations)
- Simulated SKIM spectra (100 realisations)

SWIM : Surface Waves
Investigation and Monitoring
(CNES)

- Rotating range resolved radar
- Ku-band (13.5 GHz)
- ~ 200 pulses / cycle
- 10 degree incidence
- **PRF : 5.2 kHz**
- Altitude : ~ 519 km
- **18 km x 18 km beam footprint**

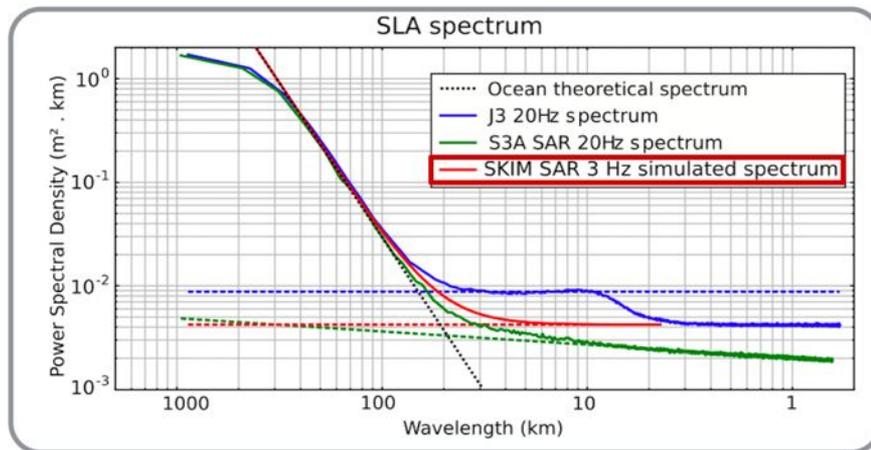
SKIM : Sea surface
Kinematics Multiscale
monitoring (ESA EE9)

- **Doppler** enabled SWIM-like sensor
- Ka-band (35 GHz)
- 1024 pulses / cycle
- 12 degree incidence
- **PRF : 32 kHz**
- Altitude : ~ 838 km
- **6 km x 6 km beam footprint**



Level-2 nadir altimetry performance

- **Scenario:** 1 month of simulated L1b data using the ESA/CNES/CLS Sentinel-3 simulation tool (configured for SKIM radar parameters) realistic scene.
- **Metric M6:** Total RSS uncertainty of sea surface height computed for the nadir beam ≤ 3.2 cm after all geophysical corrections are made.



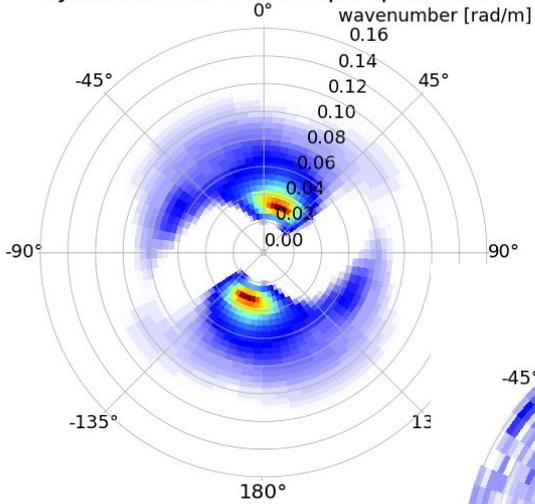
Parameter	SKIM nadir beam uncertainty (cm)	JASON-3 GDR uncertainty (cm)
Altimeter noise	<1.4	1.7
Ionosphere	0.3 ⁽¹⁾	0.5
Sea State Bias	2.0 ⁽¹⁾	2.0
Dry Troposphere	0.7 ⁽¹⁾	0.7
Wet Troposphere	1.5 ⁽²⁾	1.2
RSS Altimeter range	3.0	3.0
RMS Orbit (radial component)	1.0 ⁽³⁾	1.0
Total RSS Sea Surface Height	3.2	3.2
Total RSS Significant wave height (H_s)	9.5⁽⁴⁾	11.2

SKIM can meet Level-2 nadir altimetry performance requirements

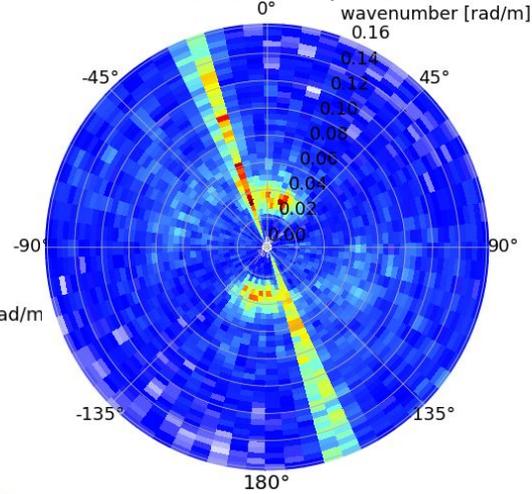
Wave directional spectrum: example



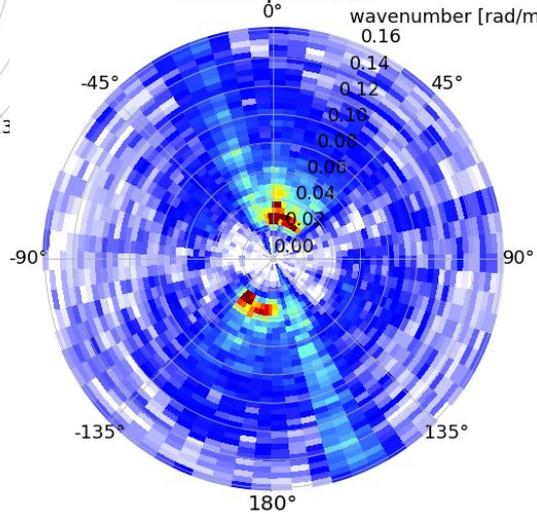
Symmetrized WW3 slope spectrum



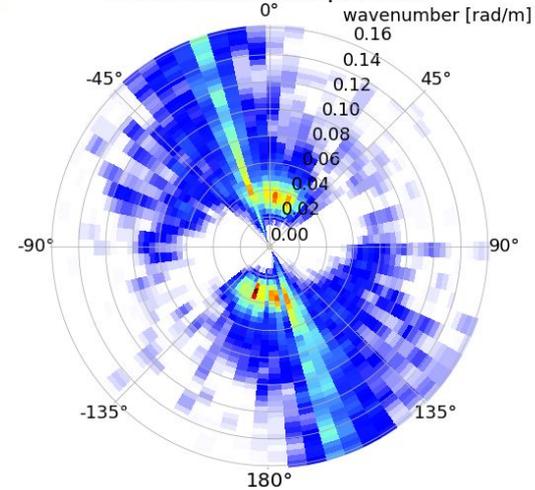
SWIM simulation spectrum



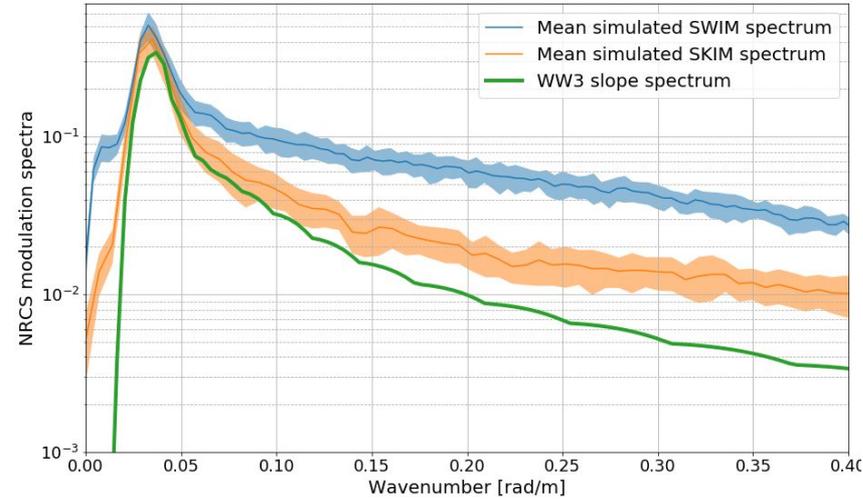
SWIM spectrum



SKIM simulation spectrum

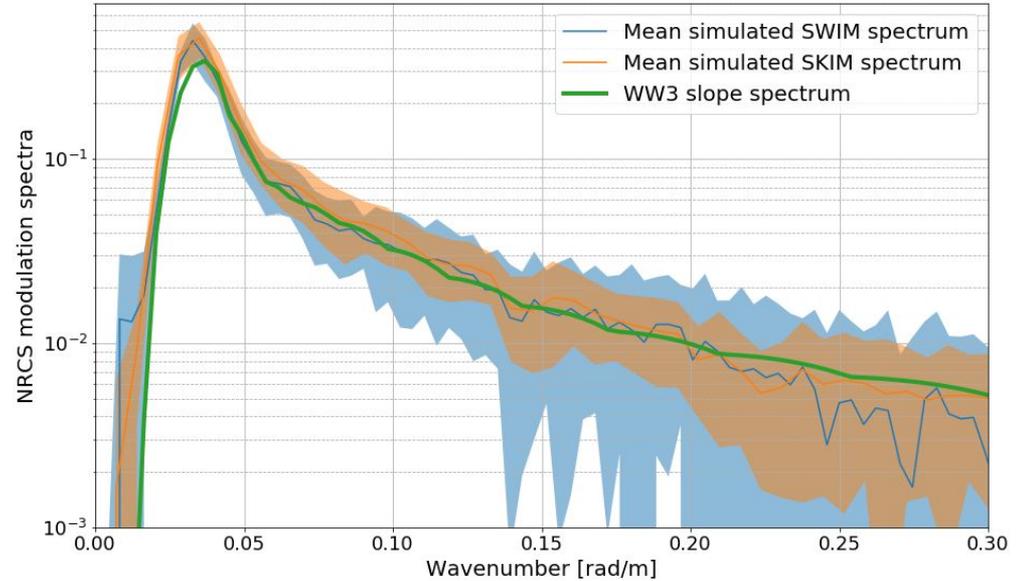


Wave directional spectrum: example



- WW3 spectrum
- Simulated SWIM spectra (100 realisations)
- Simulated SKIM spectra (100 realisations)

After speckle removal



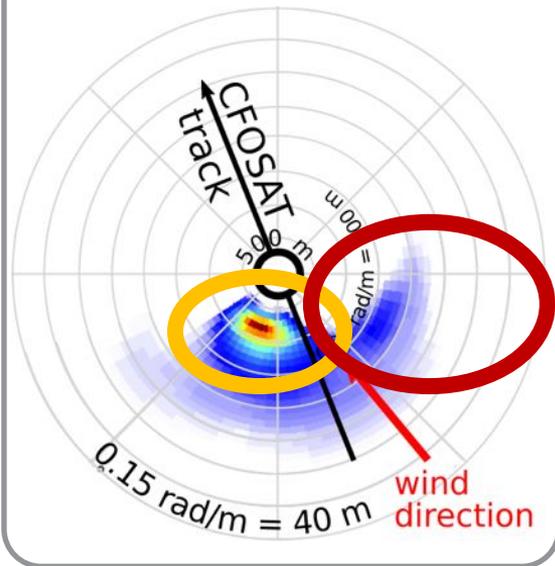
Spectrum variance is smaller on SKIM leading to better performances in terms of retrieved maximum wavenumber limits.



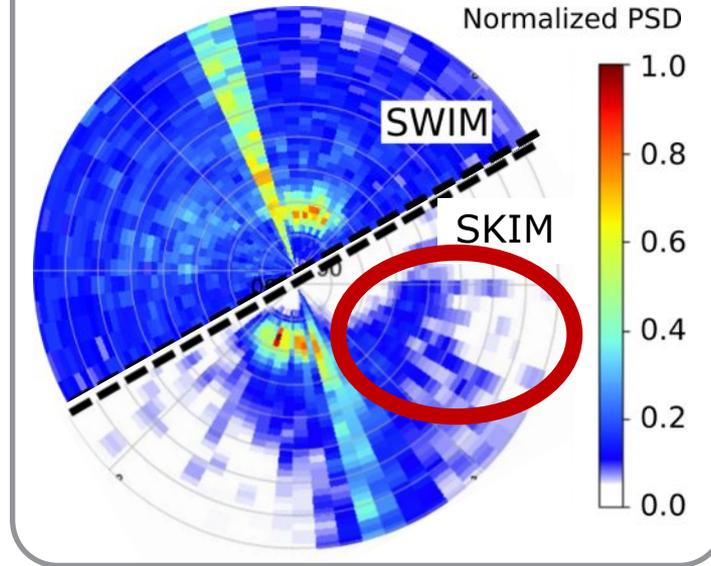
Wave directional spectrum



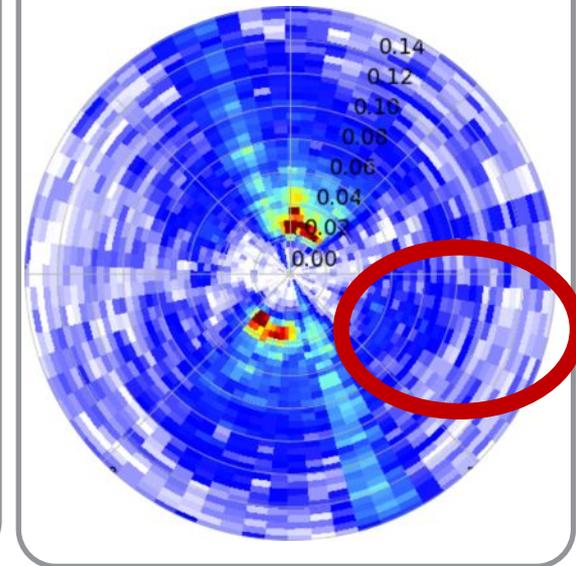
input to R3S: Wave Model WW3 $K^2 E(k, \varphi)$



R3S Simulation of SWIM (Ku) and SKIM (Ka)



Measurements: CFOSAT SWIM 29/04/19

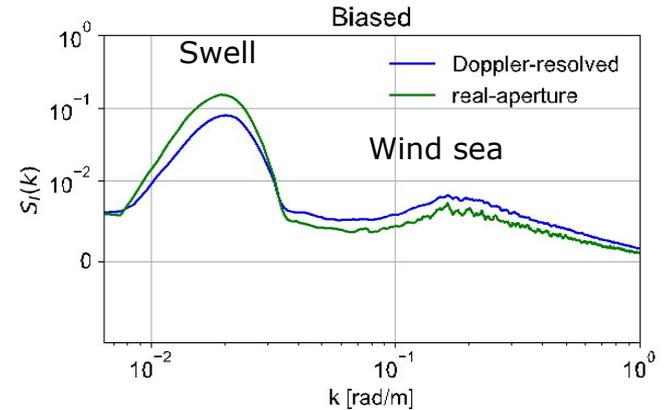


SKIM can meet wave mission performance requirements

1D range-resolved wave spectral intensity

Scenario: Simulated range-resolved intensity spectra before bias removal for a mean sea state with 12° degree beam at 45° azimuth to the swell-direction.

Results: mean of 100 simulations, with the shaded area indicated the 1- σ interval. The blue lines correspond to the Doppler-resolved case.

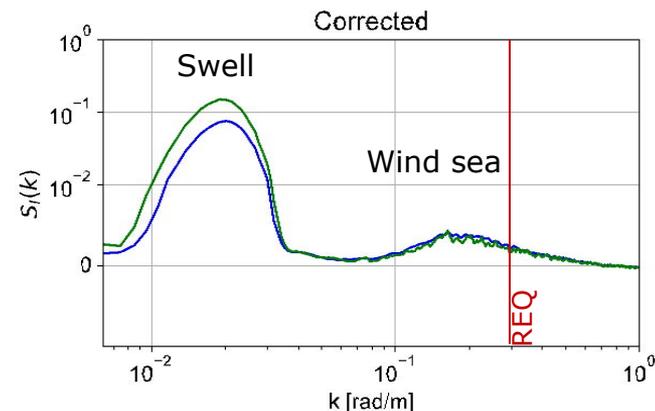


SKIM can meet wave spectral intensity performance requirements

1D range resolved wave spectral intensity

Scenario: Simulated intensity spectra after bias removal for a mean sea state with 12° degree beam at 45° azimuth to the swell-direction.

Results: mean of 100 simulations, with the shaded area indicated the 1- σ interval. The blue lines correspond to the Doppler-resolved case.



Metric M5: RMS difference between the wave spectral moment $P=[0, 1, 1.5 \text{ and } 2]$ compared to truth <10%.

Quantity				
Dominant direction, Doppler-resolved	5.5%	5.5%	5.5%	5.5%
Dominant direction, real-aperture	10.9%	10.7%	10.9%	11.2%
45° azimuth, Doppler-resolved	3%	2.5%	2.5%	2.6%
45° azimuth, real-aperture	8%	3.7%	3.6%	3.7%

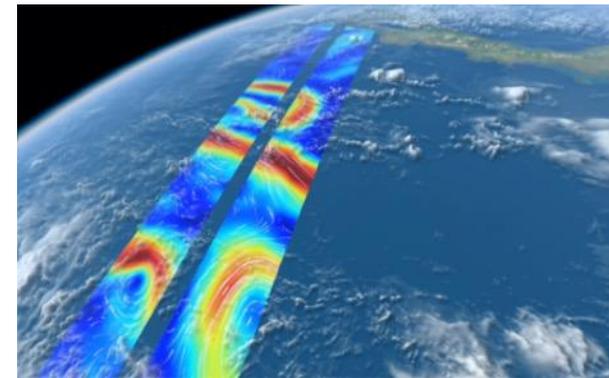
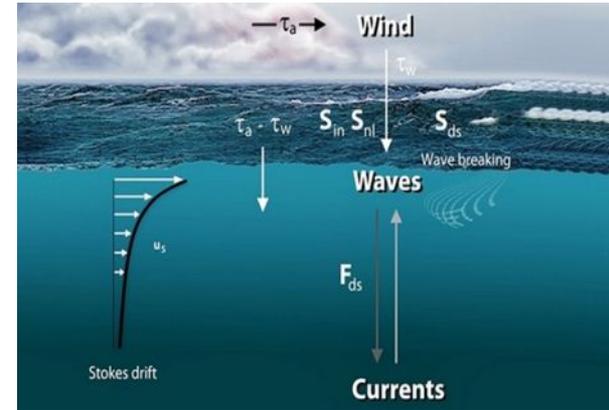
$P_0 = H_s^2$
 $P_1 =$ wave orbital velocity variance
 $P_{1.5} =$ Stokes drift
 $P_2 =$ mean square slope

SKIM can retrieve wave-spectra for wavelengths under 10 m, exceeding the requirement (30 m).

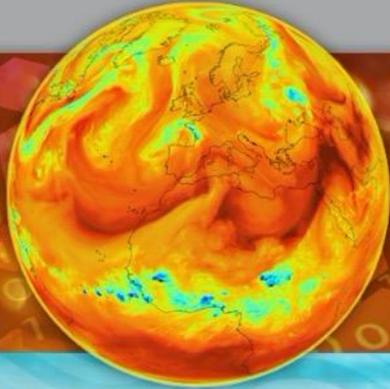
SKIM vs SWIM: Summary and Conclusions

- First global coverage Doppler Mission: *HF-radar in space*
- **Higher PRF gives lower noise: possible to resolve shorter wave components (good for Stokes drift or msv)**
- **Smaller footprint: less directive spectrum, even more so with Doppler beam sharpening**
 - possible deconvolution of measured spectrum by known system response
 - allows mapping waves where azimuth does not match wave azimuth: filling the swath

Choice of Ka-band has benefits for atmospheric effects on SKIM is a high-performance scientific mission with long term implications for future science and societal applications and Doppler oceanography.



Questions

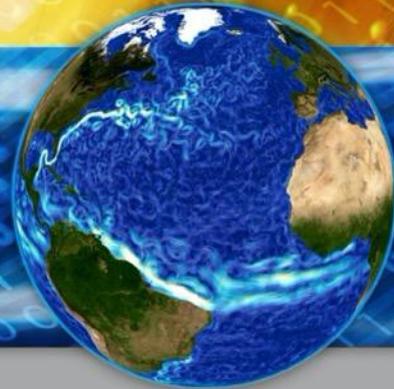


forum

→ UNDERSTANDING HOW
EARTH IS LOSING ITS COOL

skim

→ UNDERSTANDING OCEAN
SURFACE MOTION



Team SKIM

